

## AirFree ${ }^{\text {® }}$ Technology \& Cyanoacrylate

Traditional air pressure systems inject moisture filled air into the syringe reservoir activating the cyanoacrylate (CA) cure cycle. AirFree ${ }^{\circledR}$ technology eliminates moisture filled air from the dispensing process protecting the CA formulation. As a secondary safeguard Genius ${ }^{\circledR}$ CA components are made from proprietary plastics that inhibit CA bonding between components.

## AirFree ${ }^{\otimes}$ Technology \& Automation

AirFree ${ }^{\circledR}$ technology acts as an additional axis when mounted on a benchtop automation system. The precise control engineered into the $X, Y$ and $Z$ axis is now applied to the fluid delivery axis. All axes are motor driven lead screws with known speeds and can be coordinated providing the highest precision and repeatability available on a benchtop robot.

## Total Cost of Ownership

AirFree ${ }^{\circledR}$ Technology Adds Profits When Replacing Air Driven Systems
Cost of ownership, Air vs. AirFree ${ }^{\circledR}$, one fluid dispenser


## P) PQPRORB SSDAV HIGH TORQUE CA BENCHTOP AUTOMATION SYSTEM

SSDAV-HT-CA-BA Super Small Dot Any Viscosity

| BARREL SIZE | 3CC | 5CC | 10CC |
| :--- | :---: | :---: | :---: |
| MIN.VOL. (CC) | .00011 | .00019 | .00031 |
| MAX. VOL. (CC) | 3.0 | 5.0 | 10.0 |
| MIN. RATE (CC/SEC) | .003 | .005 | .008 |
| MAX. RATE (CC/SEC) | .065 | .114 | .188 |
| MAX. BACKOFF (STEPS) | 500 | 500 | 500 |
| MAX. DELAY (SEC) | 9.99 | 9.99 | 9.99 |



The SmartDispenser® SSDAV-HT-CA-BA (3-10cc) comes with 3-10cc Dispense Gun and 3, 5, 10cc Retaining Rings.

| BARREL SIZE | 30CC |
| :--- | :--- |
| MIN.VOL. (CC) | .00062 |
| MAX. VOL. (CC) | 30.0 |
| MIN. RATE (CC/SEC) | .015 |
| MAX. RATE (CC/SEC) | .370 |
| MAX. BACKOFF (STEPS) | 500 |
| MAX. DELAY (SEC) | 9.99 |

The SmartDispenser® SSDAV-HT-CA-BA (30cc) comes with 30cc Dispense Gun and 30cc Retaining Rings.

## Genius® Cyanoacrylate Dispensing Components

Genius ${ }^{\circledR}$ CA dispensing components are designed from a proprietary plastic that prevents the CA from bonding the syringe piston to the syringe barrel and the syringe tip cap to the syringe luer.

## Genius® CA FreeFlow ${ }^{\text {™ }}$ Tips and Teflon ${ }^{\circledR}$ Tips

Genius ${ }^{\circledR}$ FreeFlow ${ }^{\text {TM }}$ CA Tips and Teflon ${ }^{\circledR *}$ Tips both prevent CA from clogging the tip during the fluid dispensing process.

*Teflon is a registered trademark of the Dupont Corporation.


SMARTDISPENSER ${ }^{\circledR}$ SSDAV-HT-CA-BA 3-30CC DISPENSE STARTER KIT CONTENTS

- Foot Pedal
- Keyboard
- Mouse
- Earphone
- Video Camera
- Cisco Wireless Connectivity Device
- Needle Kit
- Manuals
- Power Supply Connection
- Universal Power Supply




## What makes the SmartDispenser® so smart?

The combination of 3 powerful platforms.

## AIR-FREE MANUFACTURING

- One program - worldwide
- Closed-loop feedback
- 6-10X more repeatable than pneumatics
- Volume base numeric dispensing
- Positive displacement via stepper motor
- Firmware proven for over a decade
- Eliminates expensive air compressor
- Designed to integrate into automation systems using PLCs


## WINDOWS 7 NETWORKING

- SD Device to MES System Networking
- Remote programming and lock out
- Real time production data
- Live video feed
- Auto e-mail of unauthorized program changes
- On screen work instruction (audio option)
- Connectivity between SmartDispensers® Desktop, Laptop and Smartphone.
- Video/Audio training and tutorials


## SMARTPHONE FUNCTIONALITY

- Touch screen
- Finger gesturing controls
- MES Networking Apps
- Custom Manufacturing Apps


## High Precision

## High Rigid Structure

A solid aluminum alloy is employed on the base and an aluminum alloy extention with a high rigid section is employed on the column

## Labyrinth Mechanism

A social labyrinth mecharism underneath the work table keeps foreign oblects (e.g. screws, liquid or dust) out.


Smooth Movement
Smooth movement is attained with the micro-step controle system

Flexible Interface

- RS-232C port for PC connection
- RS-422 port for teaching pendant
- I/O (Output 16, Input 16)


## User Friendly

## Clear Wide Screen

Wide and easy viewable teaching pendant screen Language: English/German/Japanese etc..
Measurement: mm/inch

## Simple Teaching

Using the JN C-Points software users can teach dates easily. It also has commands to operate particular jobs. Users can also create their own original software.

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Using the JN C-Points software users can teach dates easily. It also has commands to operate particular jobs. Users can also create their own original software.

## Enhanced Memory Capacity

Up to 255 programs ( 2.5 times that of the exitisting model) and 30,000 points (increased 5 -fold) can be stored as teaching data.

## Simple Sequencer

The robot has a built-in simple sequencer which functions independently (it is not necessary to add more hardware in the case of siumple PLC connection).

## P) PQPRORE® SSDAV HIGH TORQUE CA BENCHTOP AUTOMATION SYSTEM

## JANOME SPECIFICATIONS

(CL) Indicates Clean Room Compatible

| Model ${ }^{* 1}$ |  | JR2203N (CL) | JR2303N | JR2403N | JR2503N | JR2603N |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Operating Range | $X \cdot Y$ Axes (mm) | $200 \times 200$ | $300 \times 320$ | $400 \times 400$ | $510 \times 510$ | $510 \times 620$ |
|  | Z Axis (mm) | 50 | 100 | 150 |  |  |
| Maximum Portable Load | Workpiece(kg) | 7 | 11 |  |  |  |
|  | Tool(kg) | 3.5 | 6 |  |  |  |
| Maximum Speed ${ }^{* 2}$ <PTP Movement> | $X \cdot Y$ Axes ( $\mathrm{mm} / \mathrm{sec}$ ) | 700 | 800 |  |  |  |
|  | Z Axis (mm/sec) | 250 | 320 |  |  |  |
| Maximum Speed ${ }^{* 2}$ <CP Movement | $X \cdot Y \cdot Z$ Axes Combined Speed(mm/sec) | 500 | 800 |  |  |  |
| Repeatability*3 | X Axis - Y Axis (mm) | $\pm 0.006$ | $\pm 0.007$ |  | $\pm 0.008$ | $\begin{gathered} \pm 0.008(X \\ \text { Axis ) } \\ \pm 0.01 \text { (Y Axis } \\ \text { ) } \end{gathered}$ |
|  | Z Axis (mm) | $\pm 0.006$ | $\pm 0.007$ |  | $\pm 0.008$ | $\pm 0.008$ |
| External Dimensions | $\mathrm{W} \times \mathrm{D} \times \mathrm{H}(\mathrm{mm})$ (excluding cables and protrusions) | $320 \times 387 \times 540$ | $560 \times 529 \times 649.5$ | $584 \times 629 \times 799$ | $676 \times 731 \times 799$ | $788 \times 731 \times 799$ |
| Main Unit Weight(kg) |  | 18 | 35 | 42 | 46 | 48 |


| Model ${ }^{* 1}$ |  | JR2204N(CL) | JR2304N | JR2404N | JR2504N | JR2604N |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Operating Range | $\mathrm{X} \cdot \mathrm{Y}$ Axes (mm) | $200 \times 200$ | $300 \times 320$ | $400 \times 400$ | $510 \times 510$ | $510 \times 620$ |
|  | Z Axis (mm) | 50 | 100 | 150 |  |  |
|  | R Axis ( ${ }^{\circ}$ ) | $\pm 360$ |  |  |  |  |
| Maximum Portable Load | Workpiece(kg) | 7 | 11 |  |  |  |
|  | Tool(kg) | 3.5 | 6 |  |  |  |
| Maximum Speed ${ }^{* 2}$ <PTP Movement> | X - Y Axes ( $\mathrm{mm} / \mathrm{sec}$ ) | 700 | 800 |  |  |  |
|  | Z Axis (mm/sec) | 250 | 320 |  |  |  |
|  | R Axis (\%sec) | 600 | 800 |  |  |  |
| Maximum Speed* ${ }^{*}$ <CP Movement | $X \cdot Y \cdot Z$ Axes Combined Speed(mm/sec) | 500 | 800 |  |  |  |
| Repeatability*3 | X Axis - Y Axis (mm) | $\pm 0.01$ |  |  |  |  |
|  | Z Axis (mm) | $\pm 0.01$ |  |  |  |  |
|  | R Axis ( ${ }^{\circ}$ ) | $\pm 0.008$ |  |  |  |  |
| External Dimensions | $\mathrm{W} \times \mathrm{D} \times \mathrm{H}(\mathrm{mm})$ (excluding cables and protrusions) | $320 \times 387 \times 655$ | $560 \times 529 \times 840$ | $584 \times 629 \times 890$ | $676 \times 731 \times 890$ | $788 \times 731 \times 890$ |
| Main Unit Weight(kg) |  | 18 | 35 | 42 | 46 | 48 |

[^0]| JANOME SPECIFICATIONS CONTINED. |  |
| :---: | :---: |
| Drive Method | Pulse Motor |
| Control Method | PTP (Point to Point) control, CP (Continuous Path) control |
| Interpolation | 3-dimensional linear and arc interpolation |
| Teaching Method | Remote teaching (JOG)/Manual Data Input (MDI) |
| Teaching System | - Direct teaching using the optional teaching pendant <br> - Off-line teaching with JR C-Points software from a PC |
| Program Capacity | 255 Programs |
| Data Capacity ${ }^{*}$ | Up to 30,000 Points |
| External Interface | RS422 1ch (for teaching pendant) RS232C 1ch (for PC interface: COM1) <br> RS232C 2ch (for external devices: COM2, COM3) (optional) |
| External Input/Output | I/O-SYS 16 Inputs, 16 Outputs <br> I/O-1 (optional) 8 Inputs, 8 Outputs (including 4 relay outputs) |
| Simple PLC Function | 100 programs (1,000 steps/program) |
| Power Source | AC90~1323V/AC180~250V (single phase) |
| Power Consumption | 200W |

*4 Point data capacity reduces as the total function data setting/point job data/sequencer data increases, due the shared data storage area.

CE compliant models are also available.
Specifications may be modified without prior notice to improve product quality.




[^0]:    ${ }^{11} 2$-axes models are also available. (Please contact us for further information.)
    '2Maximum speed cannot be achieved when the robot is bearing its maximum portable load.
    ${ }^{3}$ Repeatability does not guarantee absolute precision.

