Programming Specification

System Name: SmartDispenserTM

Month, Year

Contents

1.	Revision Sheet	. 3
	SmartDispenser™ Program Specifications Authorization Memorandum	
3.	Purpose	. 5
	Scope	
5.	System Overview	. 5
6.	Master Capabilities Study	. 6
7.	Master List of Programs	. 6

1. Revision Sheet

Release No.	Date	Revision Description
Rev. 0	5/30/00	Master Capabilities Study

2. SmartDispenser™ Program Specifications Authorization Memorandum

I have carefully assessed the Program Specifications for the $\underline{SmartDispenser^{TM}}$. This document has been completed in accordance with the requirements of the Master Capabilities Study.

MANAGEMENT CERTIFICATION - Please check the	ne appropriate statement.
The document is accepted.	
The document is accepted pending the changes	s noted.
The document is not accepted.	
We fully accept the no changes are to be made by anyon	one but the Master Programmer.
NAME Master Programmer	DATE
NAME SmartDispenser TM Operator	DATE
NAME Production Manager	DATE
NAME Quality Manager	DATE

3. Purpose

To assure no changes are made to worldwide SmartDispensersTM dispensing assembly fluid X bonding product X.

4. Scope

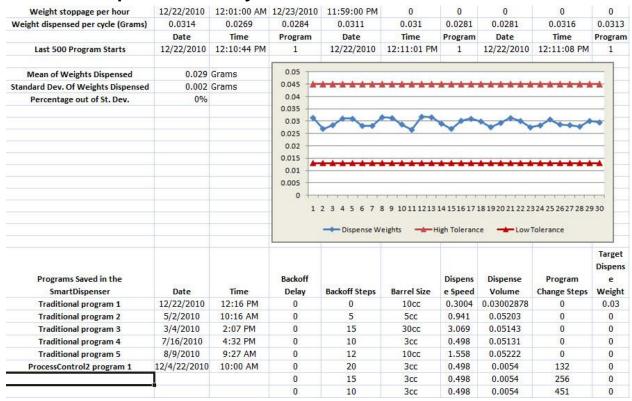
This program specification is issued to all manufacturing facilities using the SmartDispenserTM dispensing assembly fluid X bonding product X.

5. System Overview

A electro-mechanical positive displacement assembly fluid dispenser combining a stepper motor housed in a plastic gun shell, a control unit, firmware to drive the stepper motor, customer off the shelf software to support the dispenser house in a plastic control box with touchscreen.

- XXXX Corporation
- Fishman SmartDispenserTM
- Part Number **XXXXXXX**
- Assembly fluid dispenser
 - Major application: To dispense X assembly fluid in a specific location at a specific fluid volume.
 - General support system: Automation system **X**, dispense gun, network, generally accessories.

6. Master Capabilities Study



7. Master List of Programs

Program #:
Syringe Size:
Dispense Volume:
Dispenser Rate:
Reverse Motion (Backoff):
Target Dispense Weight:

+/- Tolerance %: